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**1. On covariances for fusing laser rangers and vision with sensors onboard a moving robot**

Nygards, J.; Wernersson, A.;  
Intelligent Robots and Systems, 1998. Proceedings., 1998 IEEE/RSJ International Conference on  
Volume 2, 13-17 Oct. 1998 Page(s):1053 - 1059 vol.2  
**IEEE CNF**

**2. A simulation environment to test fuzzy navigation strategies based on perceptions**

Garcia-Perez, L.; Garcia-Alegre, M.C.;  
Fuzzy Systems, 2001. The 10th IEEE International Conference on  
Volume 2, 2-5 Dec. 2001 Page(s):590 - 593 vol.3  
**IEEE CNF**

**3. Localizing mobile RF targets using multiple unmanned aerial vehicles with heterogeneous sensing capabilities**

Pack, D.; York, G.; Toussaint, G.;  
Networking, Sensing and Control, 2005. Proceedings. 2005 IEEE  
19-22 March 2005 Page(s):632 - 637  
**IEEE CNF**

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**1. Conceptual design of an integrated laser-optical measuring system for flexible manipulator**

Xu, W.L.; Tso, S.K.; Wang, X.S.;  
Systems, Man, and Cybernetics, 1996., IEEE International Conference on  
Volume 2, 14-17 Oct. 1996 Page(s):1247 - 1252 vol.2

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United States Patent Application: 0050096794

the **robot** has at least one motor for manipulating a **linkage controlling** the ...  
one **sensor onboard** the **robot** for providing **substrate support displacement** ...  
[appft1.uspto.gov/.../20050096794&RS=DN/20050096794](http://appft1.uspto.gov/.../20050096794&RS=DN/20050096794) - 41k - Supplemental Result -  
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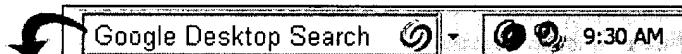
Method and apparatus for monitoring the position of a...

... for manipulating a **linkage controlling** the **displacement** of a **substrate** ...  
one **sensor onboard** the **robot** for providing **substrate support displacement** ...  
[www.freshpatents.com/Method-and-apparatus-for-monitoring-the-position-of-a-semiconductor-processing-robot...](http://www.freshpatents.com/Method-and-apparatus-for-monitoring-the-position-of-a-semiconductor-processing-robot...) - 19k - Supplemental Result - [Cached](#) - [Similar pages](#)

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